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**POF: Performance Optimized Fluid System Requirements Specification**

**16.11.2019**

**Revision 2.0**

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**Revision History**

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| --- | --- | --- |
| **Revision** | **Date** | **Explanation** |
| **1.0** | **03.11.2019** | **Initial requirements** |
| **2.0** | **16.11.2019** | **Requirements Model** |

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**1.0 Introduction**

**1.1. *Purpose***

The purpose of the performance optimized fluid (POF) system is research and apply surface reconstruction methods with intend of create more efficient particle based simulation system. The POF system should increase the efficiency of simulation by means of running it faster while occupying less memory of the computer. In detail, POF system is reconstructing the surface particles by benefiting from various research papers mentioned. The POF system approaches particles as a continuum and inspect the fluid as a whole object. Herewith, system approaches to fluids as there are no separate particles but rather the fluid is a continuous material.

**1.2. *Scope***

The POF system shall help to increase performance for simulating fluids. System reduces the necessary computation operation for particles during the simulation. Inıtially, the POF system runs the NVIDIA flex because the POF system need particles position data. The POF system works with unity engine for visualization but another program can be used for simulation.

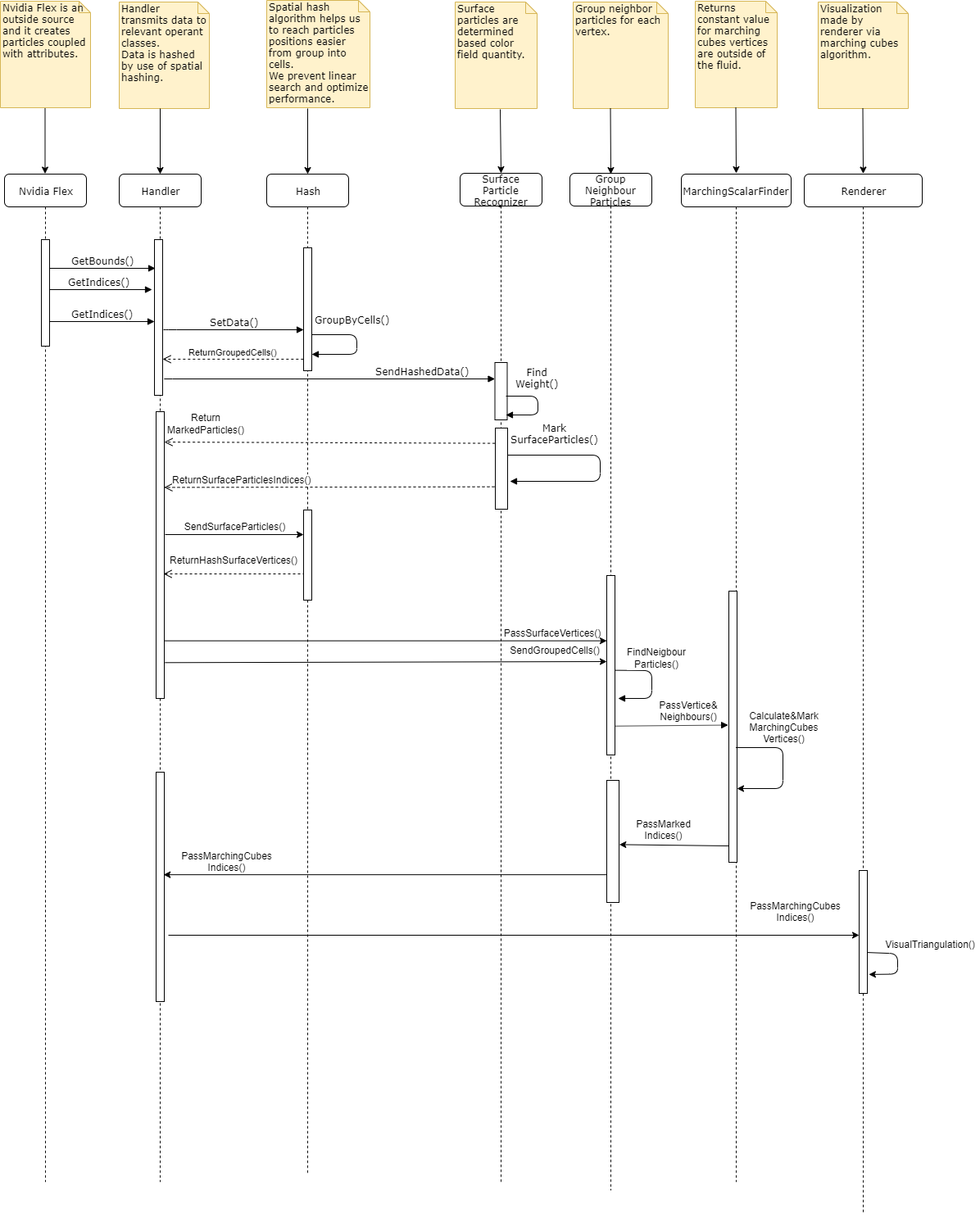
The POF system computes colour field quantity of each particle and marks all the surface particle. Surface particles are calculated and marked for the 2r distance which is the two times of a particle radius and each particle is exactly same. Marked vertices controls by handler in our code. For every surface vertex we compute every small cells in the 4 times of radius area in axis aligned bounding box (AABB). After we find the cells, we find the particles in those cells and calculate how every particle effect the other particles as a scalar value of the vertex which the method is defined in Zhu&Bridson. Lastly, for all the vertex data, we draw a cube and check those eight vertices of cube and if cell is on the surface we pass the information of the vertices for triangulation stage.

**1.3. *Overview***

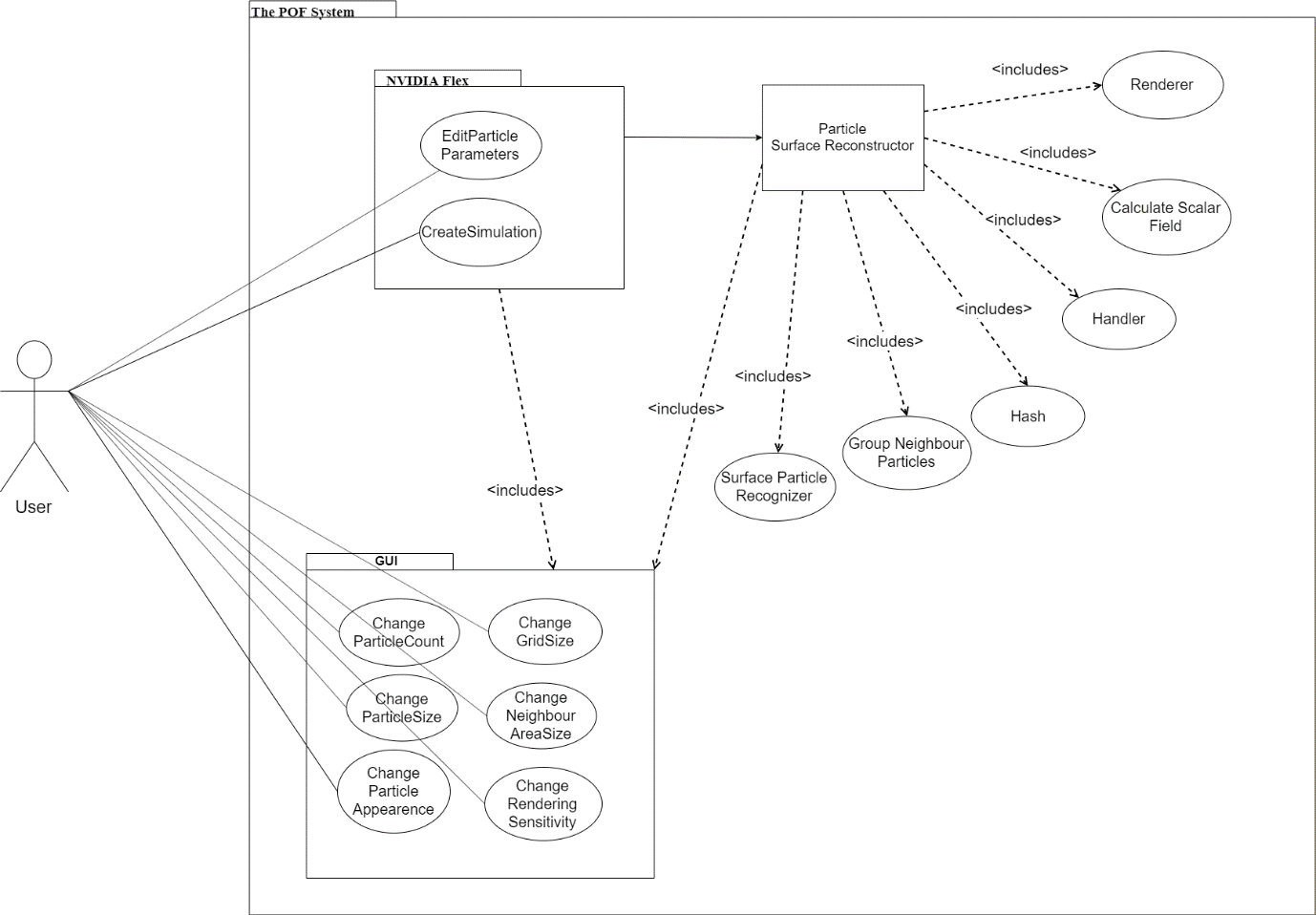
This document provides a description of the POF system. Requirements specification document involves diagrams which defines user roles in system and more importantly, explaining how system operates in the background. Document mostly focuses on the specified requirements. System functions are defined by expressing functional and non-functional requirements. The function of NVIDIA flex and how it is used in the POF system is described. User characteristics and constraints specifies that how POF system can work under which circumstances.

**2.0 Diagrams**

**2.1. *Sequence diagram***



**2.3. *Use case diagram***



**3.0 General Description**

The requirement specification document is used to provide a high-level description of the POF system. Documentation describe the mechanism and explain their roles.

***3.1. System functions***

The POF system shall retrieve the position data of the particles and AABB which is created by NVIDIA flex particle-based fluid simulation system. The POF system computes the colour field quantity of each particle and marks the surface particles and restore their vertices. The POF system calculates the cell id for each particle and calculates the scalar value of how the particles has an effect on each other by using Zhu&Bridson. System visualize the particles by using Marching cubes algorithm.

***3.2. NVIDIA flex***

NVIDIA Flex is a particle-based simulation technique for real time visual effects. It is an outside source tool for our simulation enhancement. We will use NVIDIA flex for creating particles and using particle data to process it for our algorithm. Besides, it is unnecessary to strive with particle physics for our project because it is aimed that enhancing the performance of the already existed particle-based fluid system by surface reconstruction and it is not aimed to create a fluid simulation system from scratch.

1. **Functional Requirements** 
   * 1. ***Retrieve the particle data:*** The POF system takes the particles from NVIDIA Flex which creates the particles and particle attributes such as radius adhesion, damping, and restitution. NVIDIA flex creates an axis aligned boundary box by looking the coordinates of particles. AABB is necessary preliminary step for dividing into cells.

1.)

2.)

3.)

* + 1. ***Divide into cells:*** The reason of using AABB is to make search algorithm is more efficient. Axis aligned bounding box is divided into cubic cells to analyse the particles situation. Cells are divided by the ratio of one-eight times of radius for Marching cubes algorithm initialization. Cubes are an easy way to reach vertex information. Instead of holding eight vertex data, system holds a cube position and it is a memory efficient way. The POF system use these cells to calculate the scalar values of the particles inside the cells by using zhu&bridson.
       1. **Zhu and Bridson & Surface Recognition**

**formül koyucan**

**kernel ve weight formul koy anlat**

* + - 1. **For memory efficiency & Particle classification. Başlıgı düzenle**
    1. ***Surface recognition:*** The algorithm detects surface particles and their cells so we can discard inactive cells and focus on the surface particles. This method makes system more efficient and results with better performance by discarding unnecessary cells. The POF system finds each particle
       1. **Colour field quantity**

Colour field quantity is a mathematical function that calculates a particle is affected by the other particles. Because of this function, the POF system determines that whether a particle is a surface particle.

Formul koy

1. **Kernel Function**

**formül koy**

Kernel function is necessary in kernel and particle approximation of a field function and its derivatives.

**weight func:** Gradient is a vector valued function that calculates a particle is fronting which direction. ( ??? ) small gizem

* + - 1. **Marking cells and vertices**

After we find the cells, we find the particles in those cells and calculate how every particle effect the other particles as a scalar value of the vertex which the method is defined

* + 1. ***Animating Sand as a Fluid:*** Animating Sand as a Fluid is a research paper that explains animating sand as a fluid. However, research paper also mention about it can be used in fluids which is the significant part that it will used in project. The paper mentions about surface reconstruction from particle and gives the functions and formulas in order to applying the method.

1. **Weight function**
   * 1. ***Marching cubes:*** The algorithm is used for extracting a polygonal mesh of an isosurface from a three-dimensional discrete scalar field. In this project, the marching cubes algorithm is used with the [ZB05]algorithm. [ZB05]algorithm is used in the marching cubes algorithm to get better visual outputs.
     2. ***Performance:*** This requirement can be accepted as both kind of requirement type. The project does not give this requirement as mandatory, but to achieve performance has significant importance. This requirement explained in non-functional requirements.

**4.1 Non-functional Requirements**

|  |  |
| --- | --- |
| **Non-Functional Requirements** | **Description** |
| Efficiency | The aim of the POF system is efficient memory usage. |
| Performance | The system’s performance should be increased after the application POF to the system. Due to POF system, particle simulation has higher fps rate, or it can be run at lower end devices. The existed methods will be checked whether it can be developed or not. |
| Usability | Similar fluid systems are developed in OPENGL or another various platform. However, our project will be deployed into Unity game engine which is supported on windows and macOS. |

1. **Glossary**

|  |  |
| --- | --- |
| **Term** | **Description** |
| API | Acronym for Application Programming Interface. |
| Axis Aligned Bounding Box (AABB) | Bounding volume for a set of objects is a closed volume that completely contains the union of the objects in the set. |
| Cell | Axis aligned bounding box is divided into small identical cubes. |
| Colour field quantity | It is a functionthat calculates how each particle is affected by all of the other particles. |
| CPU | Central Processing Unit. |
| GPU | Graphic Processing Unit. |
| Gradient | The directional derivative of a scalar field gives a vector field directed towards where the increment is most, and its magnitude is equal to the greatest value of the change. |
| Grid | Series of vertical and horizontal lines that are used to subdivide AABB vertically and horizontally into cells in three-dimensional space. |
| Iso-surface | An isosurface is a 3D surface representation of points with equal values in a 3D data distribution which is the 3D equivalent of a contour line. |
| Marching Cubes | Marching cubes is a computer graphics algorithm, published in the 1987 for extracting a polygonal mesh of an isosurface from a three-dimensional discrete scalar field. |
| NVIDIA Flex | NVIDIA Flex is a particle based simulation technique for real-time visual effects. |
| OPENGL | Open Graphics Library is a cross-language, cross-platform application programming interface for rendering 2D and 3D vector graphics. |
| POF | An Acronym stands for performance optimized fluid system. |
| Polygonal Mesh | Polygon mesh is the collection of vertices, edges, and faces that make up a 3D object. |
| Unity 3D | Unity is a cross-platform game engine developed by Unity Technologies. Unity is used for developing video games and simulations for consoles and mobile devices. |
| Visual Studio | Microsoft Visual Studio is an integrated development environment (IDE) from Microsoft. |

1. **User Characteristics**

The performance-optimized fluid system can be used by anyone who has an interest in particle-based fluid simulation.

**7.0 General Constrains**

A D3D11 capable graphics card with the following driver versions:

NVIDIA: GeForce Game Ready Driver 372.90 or above.

AMD: Radeon Software Version 16.9.1 or above.

In order to build the demo at least one of the following is required:

Microsoft Visual Studio 2013 or above.

G++ 4.6.3 or higher

CUDA 8.0.44 or higher

DirectX 11/12 SDK

**8.0 References**

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